

# Existence of Higher Dimensional Invariant Tori for Hamiltonian Systems

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This paper is on the persistence of higher-dimensional invariant tori for Hamiltonian systems. A KAM type theorem is established. © 1998 Academic Press

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## 1. INTRODUCTION

The celebrated KAM theory says that under a certain nondegeneracy condition, a nearly integrable Hamiltonian system preserves a family of invariant tori [1]. Recently this theory has undergone some considerable developments [2–10]. However, the study of the existence of higher dimensional invariant tori (KAM tori) for Hamiltonian systems seems quite rare. Parasyuk [7] and Hermann [13] made interesting observations on such problems. In the present paper, motivated by their work, we shall consider more general situations.

Now let us consider a Hamiltonian function,

$$H(x, y) = N(y) + P(x, y), \quad (1.1)$$

where  $N$  is a real analytic function defined on some closed bounded and connected region  $G \subset R^l$ ;  $P$  is a real analytic function defined on  $T^m \times G$ . Here  $m + l$  is even and  $m \geq l$ ;  $T^m = R^m / 2\pi Z^m$  denotes the torus of dimension  $m$ .

Let  $(T^m \times G, \omega^2)$  be a symplectic manifold, and  $I$  an analytic Hamiltonian homeomorphism from the 1-form space to vector fields, that is, let  $I$  be an antisymmetric matrix such that the relation  $\omega^2(\cdot, I\omega^1) = \omega^1(\cdot)$ , for all 1-form  $\omega^1$  defined on  $T^m \times G$  (see [11]). Then the 2-form  $\omega^2$  can be

determined in the following way:  $\{f_1, f_2\} = df_1(Idf_2) = \omega^2(Idf_1, Idf_2)$ , for all smooth functions  $f_1$  and  $f_2$  defined on  $T^m \times G$ , where  $\{\cdot, \cdot\}$  denotes the usual Poisson bracket.

Let  $\omega^2$  be invariant relative to  $T^m$ . Thus the coefficients of  $\omega^2$  and the matrix  $I$  are independent of the coordinate  $x$ . Hence the Hamiltonian system corresponding to (1.1) has the following form [12]:

$$\dot{z} = I(y)\text{grad}^T H(z), \quad (1.2)$$

where  $z = (x, y)$ , and the superscript  $T$  denotes the transpose of a vector. By Lemma 1 (see Appendix), we have that

$$I(y)\text{grad}^T N(y) = \left( \omega(y), \underbrace{0, \dots, 0}_l \right)^T.$$

Throughout this paper, we make the following hypotheses:

$$\text{rank} \left( \frac{\partial \omega}{\partial y} \right) = r, \quad \text{on } G, \quad (1.3)$$

$$\text{rank} \left\{ \omega, \frac{\partial^a \omega}{\partial y^\alpha} : \forall \alpha \in Z_+^l, 0 < |\alpha| \leq m - r + 1 \right\} = m, \quad \text{on } G, \quad (1.4)$$

where  $Z_+$  stands for the set of nonnegative integers, and  $\partial^a \omega / \partial y^\alpha = (\partial^\alpha \omega_1 / \partial y^\alpha, \dots, \partial^\alpha \omega_m / \partial y^\alpha)^T$ .

Set

$$G_\rho = \{y : \text{Re } y \in G, |\text{Im } y| < \rho\},$$

$$\Sigma_\rho = \{x : \text{Re } x \in T^m, |\text{Im } x| < \rho\}.$$

In what follows, for a vector,  $|\cdot|$  denotes its maximum norm in components; for a function,  $|\cdot|$  denotes the usual supremum norm;  $\langle \cdot, \cdot \rangle$  denotes the usual inner product in the corresponding Euclidean spaces.

Now we are in the position to state our main result:

**THEOREM A.** Assume that  $H(x, y)$  is a real analytic function on  $\Sigma_\rho \times G_\rho$ , and  $N(y)$  satisfies the conditions (1.3) and (1.4) on  $G$ . Then there exist  $\varepsilon_0 > 0$  and a nonempty Cantor set  $G_{\delta_0} \subset G$  such that  $\forall \varepsilon > 0$ , whenever  $|P| \leq \varepsilon < \varepsilon_0$ , (1.2) preserves a family of invariant tori  $IT_y$ ,  $y \in G_{\delta_0}$ , whose frequency  $\omega^\infty(y)$  satisfies

$$|\omega^\infty - \omega| \leq c \varepsilon_0^{3/4},$$

and the following measure estimate holds:

$$\text{mes}_l(G \setminus G_{\delta_0}) \leq c \delta_0^{1/(m-r+1)},$$

where  $c$  is a constant independent of  $\varepsilon$  and  $\delta_0$ ,  $\delta_0$  depends only on  $\varepsilon_0$ , and  $\delta_0 \rightarrow 0$  as  $\varepsilon_0 \rightarrow 0$ .

*Remark 1.* In [7], a nondegeneracy condition on  $\omega(y)$  is needed, and that condition does not seem obvious. But in our result, the conditions (1.3) and (1.4) are obvious, and as  $r < m$ , the unperturbed system possesses a certain degeneracy.

*Remark 2.* If  $m = l = r$ , and

$$I(y) = \begin{pmatrix} 0 & E_m \\ -E_m & 0 \end{pmatrix} \quad (E_m \text{ is the unit matrix of order } m),$$

then Theorem A is the classical KAM theorem.

*Remark 3.* The discussion of the case  $m < l$  is similar. The only difference is the measure estimate of invariant tori, which can be completed in a certain way (see [10]).

## 2. A SMALL DIVISOR PROBLEM

In this section we shall give an auxiliary result that deals with a small divisor problem. Throughout the paper we also use the following notations.

Set  $y_0 \in G$ . Write

$$D(\rho, s) = \{(x, y) : \operatorname{Re} x \in T^m, |\operatorname{Im} x| < \rho, |y - y_0| < s^2\},$$

$$[P](y) = \frac{1}{(2\pi)^m} \int_{T^m} P(x, y) dx.$$

Thus if

$$P(x, y) = \sum_{k \in Z^m} P_k e^{\sqrt{-1} \langle k, x \rangle},$$

then  $[P] = P_0$ . We shall use  $c_i$ 's to denote some positive constants depending only on the constants  $\varepsilon_{00}$ ,  $\Theta$ ,  $\tau$ ,  $M$ ,  $m$ ,  $l$ , and  $\rho$ , where  $\varepsilon_{00}$ ,  $\Theta$ ,  $\tau$ , and  $M$  will be given in the sequel.

Let  $F$  and  $N$  be real analytic functions defined on  $D(\rho, s)$ , and

$$I(y_0) \operatorname{grad}^T N(y_0) = (\omega, 0),$$

which satisfies

$$|\langle k, \omega \rangle| \geq \delta |k|^{-r}, \quad 0 \neq k \in Z^m,$$

where  $\tau \geq m(m - r + 1) - 1$  is constant,  $\delta > 0$ , and  $|k| = |k_1| + \cdots + |k_m|$ .

Set

$$N_1 = \langle \text{grad}^T N(y_0), y - y_0 \rangle.$$

We have the following.

PROPOSITION. *The equation*

$$\{\varphi, N_1\} = F - [F], [\varphi] = 0 \quad (2.1)$$

*has a unique real analytic solution  $\varphi$ , and*

$$|\varphi|_{D(\rho-\delta, s)} \leq \frac{c_1}{\delta^{m+r+2}} |F|_{D(\rho, s)}.$$

*Proof.* Write  $D = D(\rho, s)$ . Clearly,

$$\{\varphi, N_1\} = d\varphi(\text{Id}N_1) = \langle \omega, \text{grad}^T \varphi \rangle.$$

Let

$$F = \sum_{k \in Z^m} F_k(y) e^{\sqrt{-1} \langle k, x \rangle}. \quad (2.2)$$

Putting (2.2) into (2.1) yields

$$\varphi = \sum_{k \in Z^m \setminus 0} \frac{F_k(y)}{\langle k, \omega \rangle} e^{\sqrt{-1} \langle k, x \rangle}.$$

By Cauchy's estimate we have

$$\begin{aligned} |\varphi|_{D(\rho-\delta, s)} &\leq \sum_{k \in Z^m \setminus 0} \frac{|F_k(y)|}{|\langle k, \omega \rangle|} e^{|k|(\rho-\delta)} \\ &\leq \sum_{k \in Z^m \setminus 0} \frac{|k|^\tau}{e^{|k|\delta}} |F|_D \\ &\leq \sum_{j=1}^{\infty} \frac{2^m j^{m+\tau-1}}{\delta e^{j\delta}} |F|_D \quad (\text{see [1]}) \\ &\leq \frac{c_2}{\delta^{m+\tau+2}} \sum_{j=1}^{\infty} \frac{1}{j^{2+[\tau]-\tau}} |F|_D \quad ([\tau] \text{ is the integer part of } \tau) \\ &\leq \frac{c_1}{\delta^{m+\tau+2}} |F|_{D(\rho, s)}. \end{aligned}$$

## 3. PROOF OF THEOREM A

Fix  $y_0 \in G$ , and write

$$\begin{aligned} N &= N(y_0) + \langle \text{grad}^T N(y_0), y - y_0 \rangle + \frac{1}{2!} \left\langle \frac{\partial^2 N}{\partial y^2}(y_t)(y - y_0), y - y_0 \right\rangle \\ &= N_0 + N_1 + \hat{N}, \end{aligned} \quad (3.1)$$

where  $y_t = y_0 + t(y - y_0)$ ,  $0 \leq t \leq 1$ .

*Remark 4.* In general, we may take

$$N = N_0 + N_1(y) + \hat{N}(x, y),$$

where  $\hat{N}(x, y) = \langle Q(x, y)(y - y_0), y_0 - y \rangle$ . By (1.2) it is easy to see that  $\{(x, y): x \in T^m, y = y_0\}$  is an invariant torus of dimension  $m$  of Hamiltonian  $N$ .

Since  $\text{grad}^T N(y)$  and  $\partial^2 N / \partial y^2$  are bounded on  $G$ , we may assume that on  $D(\rho, s')$ ,

$$|N_1| \leq \mu_1^0 (s')^2, \quad |\hat{N}| \leq \mu_2^0 (s')^4, \quad s' \leq s, \quad (3.2)$$

where  $\mu_1^0$  and  $\mu_2^0$  are constants depending on  $G$ .

## 1. Outline of the proof and estimate of the measure

Choose convergent sequences:

$$\varepsilon_{i+1} = \varepsilon_i^{9/8}, \quad \delta_i = \varepsilon_i^{1/8(m+\tau+3)}, \quad s_i = \varepsilon_i^{1/8},$$

$$\rho_{i+1} = \rho_i - 6\delta_i, \quad i = 0, 1, 2, \dots,$$

where constant  $\varepsilon_0$  satisfies conditions (A)–(H) listed below, and  $\rho_0 = \rho$ . Set

$$\begin{aligned} D_j^i &= D\left(\rho_i - j\delta_i, \frac{7-j}{8}s_i\right) \\ &= \left\{(x, y): \text{Re } x \in T^n, |\text{Im } x| < \rho_i - j\delta_i, |y| < \left(\frac{7-j}{8}s_i\right)^2\right\}, \\ &\quad 0 \leq j \leq 6. \end{aligned}$$

Assume that the Hamiltonian function  $N + P$  on  $D_0^i$  is, by a symplectic transformation, reduced into  $N^i + P^i$ , where

$$N^i = N_0^i + N_1^i + \hat{N}^i, \quad (3.3)_i$$

$$|N_1^i|_{D(\rho_i, s')} \leq \mu_1^i (s')^2, \quad |\hat{N}^i|_{D(\rho_i, s')} \leq \mu_2^i (s')^4, \quad s' \leq s_i \quad (3.4)_i$$

$$|P^i| \leq \varepsilon_i. \quad (3.5)_i$$

Set

$$O_i = \{y \in G: |\langle k, \omega^i(y) \rangle| \geq \delta_i |k|^{-r}, 0 \neq k \in Z^m\}.$$

Take  $y_0 \in O_i$ . Then

$$I(y_0) \text{grad}^T N_1^i(y_0) = (\omega^i(y_0), 0).$$

Introduce a symplectic transformation  $\Phi_i$  such that

$$(N^i + P^i) \circ \Phi_i = N^{i+1} + P^{i+1}.$$

We are going to prove that  $N^{i+1} + P^{i+1}$  satisfies the corresponding expressions (3.3)<sub>i+1</sub>–(3.5)<sub>i+1</sub>. If

$$y_0 \in \bigcap_{k=0}^{i+1} O_k \neq \emptyset,$$

then the iteration processes can continue. Set

$$\begin{aligned} N^{i+1} &= N^i + R^i \\ &= (N_0^i + [P^i](y_0)) + \left( N_1^i(y) + \left\langle \frac{\partial}{\partial y} [P^i](y_0), y - y_0 \right\rangle \right) \\ &\quad + (\hat{N}^i(x, y) + \hat{R}^i(x, y)) \\ &= N_0^{i+1} + N_1^{i+1} + \hat{N}^{i+1}, \end{aligned} \tag{3.6}_i$$

where  $R^i$  is determined by the following (3.11). Without loss of generality, we assume

$$\Theta \leq |I|_G \leq \Theta^{-1}, \tag{3.7}$$

where

$$|I|_G = \max_{y \in G} \sup_{|z|=1} \frac{|Iz|}{|z|}, \quad z = (x, y).$$

From (3.5)<sub>i</sub> and Cauchy's estimate, we derive

$$|\text{grad}^T [P^i]|_{D_0^i} \leq \frac{c_3}{s_i^2} \varepsilon_i^{3/4}. \tag{3.8}$$

By (3.6)–(3.8), we see that as

$$\varepsilon_0 < \min \left\{ \left( \frac{1}{2} \right)^{32}, \frac{\varepsilon_{00}}{2c_3} \Theta \right\}, \tag{A}$$

the following inequality holds on  $D_1^{i+1}$ :

$$\begin{aligned} |\omega^{i+1} - \omega^0| &\leq \sum_{k=0}^i |\omega^{k+1} - \omega^k|_{D_1^k} \\ &\leq \sum_{k=0}^i |I|_G |\text{grad}^T [P^{k+1}]|_{D_1^k} \\ &\leq c_3 \Theta^{-1} \sum_{k=0}^i \varepsilon_k^{3/4} < \varepsilon_{00}, \end{aligned}$$

where  $\omega^0 = \omega$ , and  $\varepsilon_{00}$  is given in the Appendix. Hence

$$|\omega^{i+1}| \leq |I|_G |\text{grad}^T N|_G + \varepsilon_{00} \leq M + \varepsilon_{00}, \quad (3.10)$$

where  $M \geq \max\{|I|_G |\text{grad}^T N|_G, \mu_2^0 + 2c_{15}, \mu_1^0 + 2c_{14}\}$ , and  $c_{14}$  and  $c_{15}$  will be determined below.

Set

$$G_{\delta_0} = \bigcap_{i=0}^{\infty} O_i.$$

By (3.9) and Lemma 3 we obtain

$$\begin{aligned} \text{mes}_l(G \setminus G_{\delta_0}) &\leq \sum_{i=0}^{\infty} \text{mes}_l(G \setminus O_i) \\ &\leq \sum_{i=0}^{\infty} \text{mes}_l(G \setminus O_i) \\ &\leq c \sum_{i=0}^{\infty} \delta_i^{1/(m-r+1)} \\ &\leq 2c \delta_0^{1/(m-r+1)}. \end{aligned}$$

Here we have used the inequality

$$\varepsilon_0 < \left(\frac{1}{2}\right)^{64(m-r+1)(m+r+3)}. \quad (B)$$

## 2. KAM iteration

We prove only one cycle of iteration processes, to say, from the  $i$ th step to the  $i+1$ th step. For simplicity, we omit notation  $i$  and denote  $i+1$  by  $+$ .

We need to construct functions  $S = S_0 + S_1$ ,  $R = R_0 + R_1 + \hat{R}$  such that

$$\{S, N\} = P - R, \quad [S] = 0, \quad [R_0 + R_1] = R_0 + R_1. \quad (3.11)$$

Let  $\Phi^t$  be the flow determined by the vector field  $IdS$ . Define  $\Phi = \Phi^1$ . Then  $\Phi$  is a symplectic transformation. On the basis of the fact

$$\frac{d}{dt} F \circ \Phi^t = \{F, S\} \circ \Phi^t$$

and Taylor's formula, we have

$$(N + P) \circ \Phi = N^+ + \int_0^1 \{tP + (1-t)R, S\} \circ \Phi^t dt, \quad (3.12)$$

$$N^+ = N + R, \quad P^+ = \int_0^1 \{tP + (1-t)R, S\} \circ \Phi^t dt. \quad (3.13)$$

Using (3.11) yields

$$\{S_0, N_1\} = P(x, y_0) - R_0, \quad [S_0] = 0, \quad [R_0] = R_0, \quad (3.14)$$

$$\begin{aligned} \{S_1, N_1\} &= \left\langle \frac{\partial P}{\partial y}(x, y_0), y - y_0 \right\rangle - \left\langle S_0, \frac{1}{2} \left\langle \frac{\partial^2 N}{\partial y^2}(y_0)(y - y_0), y - y_0 \right\rangle \right\rangle \\ &\quad - R_1, \quad [S_1] = 0, \quad [R_1] = R_1. \end{aligned} \quad (3.15)$$

Take

$$R_0 = [P](y_0) \quad R_1 = \left\langle \left[ \frac{\partial P}{\partial y} \right](y_0), y - y_0 \right\rangle, \quad (3.16)$$

$$\hat{R} = \hat{P} - \left\langle S_0, \hat{N} - \frac{1}{2} \left\langle \frac{\partial^2 N}{\partial y^2}(y_0)(y - y_0), y - y_0 \right\rangle \right\rangle - \{S_1, \hat{N}\}, \quad (3.17)$$

$$\hat{P} = P - P(x, y_0) - \left\langle \frac{\partial P}{\partial y}(x, y_0), y - y_0 \right\rangle. \quad (3.18)$$

Utilizing (3.5), (3.14), (3.16), and the proposition, we have

$$|S_0|_{D_1} \leq \frac{c_4}{\delta^{m+r+2}} \varepsilon. \quad (3.19)$$



By (3.16), (3.19), and Cauchy's estimate, we obtain

$$\begin{aligned}
& \left| \left\langle \frac{\partial P}{\partial y}(x, y_0), y - y_0 \right\rangle - \left\langle S_0, \frac{1}{2} \left\langle \frac{\partial^2 N}{\partial y^2}(y_0)(y - y_0), y - y_0 \right\rangle \right\rangle - R_1 \right|_{D_2} \\
& \leq 2 \left| \left\langle \frac{\partial P}{\partial y}(x, y_0), y - y_0 \right\rangle \right|_{D_2} \\
& \quad + \left| \left\langle S_0, \frac{1}{2} \left\langle \frac{\partial^2 N}{\partial y^2}(y_0)(y - y_0), y - y_0 \right\rangle \right\rangle \right|_{D_2} \\
& \leq c_4 \varepsilon + \frac{c_1 \varepsilon}{\delta^{m+r+3}} \cdot \mu_2 |I|_G \\
& \leq \frac{c_5}{\delta^{m+r+3}} \varepsilon (c_5 = M \Theta^{-1}(c_1 + c_4), \mu_2^0 + 2c_{15} \leq M). \quad (3.20)
\end{aligned}$$

Here we have used the inequality  $\mu_2 \leq \mu_2^0 + 2c_{15}$ ! The proof will be given in the sequel. Applying the proposition yields

$$|S_1|_{D_3} \leq \frac{c_1}{\delta^{m+r+2}} \cdot \frac{c_5}{\delta^{m+r+3}} \varepsilon \leq \frac{c_6}{\delta^{2m+2\tau+5}} \varepsilon. \quad (3.21)$$

From (3.18) and (3.4) we see

$$|\hat{P}|_{D_1} \leq c_7 \varepsilon, \quad \max \left\{ \left| \frac{\partial \hat{N}}{\partial y} \right|_{D_1}, \left| \frac{\partial^2 \hat{N}}{\partial y^2} \right|_{D_1} \right\} \leq c_8 \mu_2 \leq c_8 M. \quad (3.22)$$

By (3.17), (3.19)–(3.22), (3.7), and Cauchy's estimate, we have

$$\begin{aligned}
|\hat{R}|_{D_4} & \leq c_7 \varepsilon + \frac{c_4 \varepsilon}{\delta^{m+r+3}} \cdot 2c_8 M |I|_G + \frac{c_6}{\delta^{2m+2\tau+6}} \varepsilon \cdot c_8 M |I|_G \\
& \leq \frac{c_9}{\delta^{2m+2\tau+6}} \varepsilon. \quad (3.23)
\end{aligned}$$

(3.19) and (3.21) imply

$$|S|_{D_3} \leq \frac{c_{10}}{\delta^{2n+2\tau+6}} \varepsilon. \quad (3.24)$$

From (3.13), (3.23), (3.24), and Cauchy's estimate, it follows that

$$\begin{aligned}
|P^+|_{D_4} & \leq |\{P, S\}|_{D_4} + |\{R, S\}|_{D_4} \\
& \leq \frac{c_{11} \Theta^{-1}}{s^2 \delta^{2m+2\tau+6}} \varepsilon^2 + \frac{c_{12}}{s^2 \delta^{4m+4\tau+12}} \varepsilon^2 \\
& \leq \frac{c_{13}}{s^2 \delta^{4m+4\tau+12}} \varepsilon^2.
\end{aligned}$$

By the choice of  $s$  and  $\delta$ , we have

$$|P^+| \leq \frac{1}{2} \varepsilon_+ < \varepsilon_+, \quad (3.25)$$

provided

$$\varepsilon_0 < (2c_{13})^{-8}. \quad (C)$$

Now we verify  $(3.4)_+$  for  $N^+$ . By  $(3.6)_+$  we obtain

$$\begin{aligned} |N_1^+|_{D(\rho-6\delta, s')} &\leq \left( \mu_1 + c_{14} \frac{\varepsilon}{s^2} \right) (s')^2 \leq \mu_1^+ (s')^2, & s' &\leq \frac{1}{8} s, \\ |\hat{N}^+|_{D(\rho-6\delta, s')} &\leq \left( \mu_2 + c_{15} \frac{\varepsilon}{s^4} \right) (s')^4 \leq \mu_2^+ (s')^4, & s' &\leq \frac{1}{8} s. \end{aligned}$$

As

$$\varepsilon_0 < \left( \frac{1}{8} \right)^{64}, \quad (D)$$

we also have

$$\begin{aligned} s_+ &< \frac{1}{8} s, \\ \mu_1 &\leq \mu_1^0 + 2c_{14} \leq M, \\ \mu_2 &\leq \mu_2^0 + 2c_{15} \leq M. \end{aligned}$$

These imply  $(3.4)_+$ .

### 3. Estimates of coordinates

By (3.24) and Cauchy's estimate we derive

$$\left| \frac{\partial S}{\partial x} \right|_{D_4} \leq \frac{c_{14}}{\delta^{2m+2\tau+6}} \varepsilon, \quad \left| \frac{\partial S}{\partial y} \right|_{D_4} \leq \frac{c_{15}}{s^2 \delta^{2m+2\tau+6}} \varepsilon.$$

Choosing

$$\varepsilon_0 < (c_{14} + c_{15})^{-8}, \quad (E)$$

we obtain

$$|\Phi - \text{id}|_{D_5} \leq \frac{c_{14} + c_{15}}{s^2 \delta^{2m+2\tau+6}} \varepsilon < \varepsilon^{3/8} < s_+ < \delta_+. \quad (3.26)$$

Hence  $\Phi$  is well defined on  $D(\rho_+, s_+)$  and

$$\Phi: D(\rho_+, s_+) \rightarrow D_5. \quad (3.27)$$

#### 4. Completion of the proof

Choose  $y_0 \in G_{\delta_0}$  and define  $\Psi_i = \Phi_0 \circ \Phi_1 \circ \cdots \circ \Phi_{i-1}$ . Then as

$$\varepsilon_0 < \min \left\{ \left( \frac{1}{2} \right)^{64(m+r+3)}, \left( \frac{\rho}{24} \right)^{8(m+r+3)} \right\}, \quad (F)$$

we have

$$\rho_\infty = \rho - 6 \sum_{i=0}^{\infty} \delta_i > \frac{\rho}{2}.$$

Set

$$D_\infty = \{x: \operatorname{Re} x \in T^m, |\operatorname{Im} x| < \rho_\infty\} \times \{y = y_0\}.$$

Using (3.26) and (D) yields that on  $D_\infty$ ,

$$|\Psi_i - \operatorname{id}| \leq \sum_{k=1}^i |\Psi_k - \Psi_{k-1}| \leq \sum_{k=1}^i \varepsilon_i^{3/8} < 2\varepsilon_0^{3/8}.$$

Hence  $\{\Psi_i\}$  is uniformly convergent on  $D_\infty$ . As in (3.9), from (A) we see

$$|\omega^\infty(y) - \omega(y)| < c_{16} \varepsilon_0^{3/4}, \quad y \in G_{\delta_0},$$

where  $\omega^\infty = \lim_{i \rightarrow \infty} \omega^i(y)$ . By (3.26) we have

$$\left| \frac{\partial \Phi_i}{\partial(x_i, y_i)} - E \right| \leq \frac{c_{17}}{s_i^2 \delta_i} \varepsilon_i^{3/8} < \varepsilon_i^{1/24},$$

as

$$\varepsilon_0 < c_{17}^{-24}, \quad (G)$$

where  $E$  is the unity matrix. Thus

$$\left| \frac{\partial \Psi_i}{\partial(x_i, y_i)} \right|_{D_\infty} \leq \sum_{k=0}^{i-1} (1 + \varepsilon_k^{1/24}) < \sum_{i=0}^{\infty} \left( \frac{1}{3} \right)^k = \frac{3}{2},$$

whenever

$$\varepsilon_0 < \left( \frac{1}{2} \right)^{132}. \quad (H)$$

Therefore  $\{\partial \Psi_i / \partial(x_i, y_i)\}$  converges on  $D_\infty$ .

By (3.15)–(3.16) and (3.23) we may assume that

$$\hat{R}^i(x, y) = O((y - y_0)^2)$$

uniformly holds on  $D_4^i$ . Hence the system

$$\dot{z} = I(y) \operatorname{grad}^T N^{i+1}(z)$$

has an invariant torus  $\{(x, y): x \in T^m, y = y_0\}$ . Using the convergence of  $\{\Psi_i\}$  and  $\{\partial \Psi_i / \partial(x_i, y_i)\}$ , we derive that  $H^\infty = H \circ \Psi^\infty = N^\infty$ ,  $\Psi^\infty = \lim_{i \rightarrow \infty} \Psi^i$ , has an invariant torus  $\{(x, y): x \in T^m, y = y_0\}$  with the frequency  $\omega^\infty(y_0)$ . This completes the proof.

#### 4. APPENDIX

Now we list some lemmas that have been used in previous sections.

LEMMA 1 [7]. *Consider the Hamiltonian system*

$$\dot{z} = I(y) \operatorname{grad}^T H(z), \quad z = (x, y). \quad (4.1)$$

If  $H(z) = H(y)$ , then (4.1) has the form

$$\dot{x} = \omega(y), \quad \dot{y} = 0,$$

where  $\omega(y) = (\omega_1(y), \dots, \omega_m(y))^T$ .

LEMMA 2 [9]. *Let  $O \subset R^n$  be a bounded and connected region, and let  $g$  and  $\bar{g}$  be real analytic  $n$ -dimensional vector-valued functions, on  $\bar{O}$ , such that*

$$\operatorname{rank} \left( \frac{\partial g}{\partial y} \right) = r,$$

$$\operatorname{rank} \left\{ g, \frac{\partial^\alpha g}{\partial y^\alpha} : \forall \alpha, |\alpha| \leq n - r + 1 \right\} = n;$$

then there is  $\varepsilon_0 > 0$  such that as  $\delta$  is sufficiently small and  $|\bar{g}| < \varepsilon_0$ , the set

$$O_\delta = \{y \in O : |\langle k, g(y) + \bar{g}(y) \rangle| \geq \delta |k|^{-\tau}, 0 \neq k \in \mathbb{Z}^n\}$$

is a nonempty Cantor set, and

$$\operatorname{mes}_n(O \setminus O_\delta) \leq c \delta^{1/(n-r+1)},$$

where  $c$  is independent of  $\alpha, \bar{g}$ .

LEMMA 3. Assume that  $\omega(y)$  satisfies conditions (1.3) and (1.4), and  $\tilde{\omega}(y)$  is a real analytic  $m$ -dimensional vector-valued function. Then there is  $\varepsilon_{00} > 0$  such that as  $\delta$  is sufficiently small and  $|\tilde{\omega}| < \varepsilon_{00}$ , the set

$$G_\delta = \{y \in G: |\langle k, \omega(y) + \tilde{\omega}(y) \rangle| \geq \delta |k|^{-\tau}, 0 \neq k \in \mathbb{Z}^m\}$$

is a nonempty Cantor set, and

$$\text{mes}_l(G \setminus G_\delta) \leq c \delta^{1/(m-r+1)},$$

where  $c$  is independent of  $\alpha$  and  $\tilde{\omega}$ .

*Proof.* Apply Lemma 2 and Fubini's theorem.

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